Appl. No.: 10/718,913 Date: November 7, 2007

LIST OF PATENTS AND PUBLICATIONS FOR APPLICANTS' INFORMATION DISCLOSURE STATEMENT

INFORMATION DISCLOSURE STATEMENT BY APPLICANT

Application Number	10/718,913
Filing Date	November 21, 2003
Inventor	McBean et al
Art Unit	3772
Examiner	Brown, Michael
Atty Docket	1118/A04

Non-Patent References			
Examiner's Initials	Ref. No.	Document Number, Publication Date, Inventor	
	BQ	Lum, et al., "A Robotic System for Upper-Limb Exercises to Promote Recovery of Motor Function Following Stroke", ICORR '99: International Conference on Rehabilitation Robitics, Stanford, CA, pages 235-239	
	BR	Lum, et al., "Quantification of Force Abnormalities During Passive and Active-Assisted Upper-Limb Reaching Movements in Post-Stroke Hemiparesis", 1999, IEEE Trans on Biomed, Vol 46, No 6, pages 652-662	
	BS	Lum, et al., "Robotic Assist Devices for Bimanual Physical Therapy Preliminary Experiments", 1993, IEEE Transactions on Rehabilitation Engineering, Vol. 1, No. 3, pages 185-191	
	BT	Parsons, et al., "An Adaptable User Interface and Controller for a Rehabilitation Robotoc Arm, 1997, ICAR, pages 919-923	
	BU	Popovic, et al., "Hybrid Assistance System-The Motor Neuroprosthesis", 1989, IEEE Transactions on Biomedical Engineering, Vol. 36, No. 7, pages 729-737	
	BV	Rabischong, et al., "Control and Command of a Six Degrees of Freedom Active Electrical Orthosis for Paraplegic Patent", 1990, IEEE International Workshop on Intelligent Robots and Systems, pages 987-991	
	BW	Reinkensmeyer, et al., "Guidance-Based Quantification of Arm Impairment Following Brain Injury: A Pilot Study", 1999, IEEE Transactions on Rehabilitation Engineering, Vol 7, No. 1, pages 1-11	
	BX	Romilly, et al., "A Functional Task Analysis and Motion Stimulation for the Development of a Powered Upper-Limb Orthosis", 1994, IEEE Transactions on Rehabilitation Engineering, Vol. 2, No 3, pages 119-129	

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	BY	Timoszyk, et al., "Robot-Assisted Locomotion Training after Spinal Cord Injury – Comparison of Rodent Stepping in Virtual and Physical Treadmill Environments", Department of Mechanical and Aerospace Engineering and Center for Biomedical Engineering, University of California, Irvine, 1990 IEEE International Conference, pages 1-14	
	BZ	Triolo, et al., "The Theoretical Development of a Multichannel Time- Series Myoprocessor for Simultaneous Limb Function Detection and Muscle Force Estimation", 1989, IEEE Transactions on Biomedical Engineering, Vol. 36, No. 10, pages 1004-1017	
	CA	Wu, et al., "A Study of Neuromuscular-like Control in Rehabilitation Robot", Proceedings of the 1996 IEEE International Conference on Rotobics and Automation, Minneapolis, MN, 0-7803-2988-4/96, April 1996, pages 1178-1183	
	СВ	Zardoshti-Kermani, et al., "EMG Feature Evaluation for Movement Control of Upper Extremity Prostheses", 1995, IEEE Transactions on Rehabilitation Engineering, Vol. 3, No. 4, pages 324-333	

Examiner Signature:	
Date Considered:	

EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609; draw a line through the citation *if not* in conformance and not considered. Include copy of this form with next communication to applicant.

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Identification of Person Making This Information Disclosure Statement

The person making this statement is the practitioner who signs below on the basis of the information supplied by the inventor and in the practitioner's file.

Respectfully submitted,

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DATE: November 7, 2007

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